

## A1 COMPUTER FUNDAMENTALS · A1.3

# Operating systems and control systems

How an **operating system** shares the hardware, schedules the CPU, and handles devices, plus the **control systems** that keep a physical process on target. Multitasking and resource allocation are HL only.

## 01 Role of the OS

**Layer** Sits between apps and the hardware.

**Shares** CPU, memory, storage, and devices.

**Protects** Keeps each process in its own space.

**Examples** Windows, macOS, Linux, Android, iOS.

## 02 OS functions

**Process** Schedules and tracks running processes.

**Memory** Allocates RAM, isolates spaces, virtual memory.

**File** Organises files and access rights.

**Device** Drivers talk to keyboards, disks, printers.

**Security** Authentication, permissions, logging.

**UI** Desktop or command line.

## 03 Scheduling algorithms

### 01

#### FCFS

First come, first served, in arrival order. Non-preemptive. Simple, but a long job blocks the queue.

### 02

#### Round robin

Fixed quantum, rotate the ready queue. Preemptive and fair, keeps the system responsive.

### 03

#### Priority

Highest priority runs first. Can starve low-priority jobs unless priorities are adjusted.

**04 Polling vs interrupts**

● **Polling**

CPU loops, checking each device. Simple but wastes cycles. Good for frequent or predictable events.

● **Interrupt**

Device signals the CPU, which runs an **ISR** then resumes. Efficient for rare or unpredictable events.

**Weigh** Event frequency, CPU overhead, power, latency.

**05 Multitasking · HL only**

**Context switch**

Save one process state, load the next.

**Virtual memory**

Run more than fits in RAM.

**Paging**

Move fixed-size pages between RAM and disk.

**Contention**

Processes compete for CPU, memory, files.

**Deadlock**

Each holds what the others need; all stall.

**06 Control systems · input, process, output, feedback**

**Sensor**

Measures the current output such as temperature, speed, or position. A transducer converts one form of energy into another.

**INPUT**

**Controller**

Compares the measurement to the set point, finds the error, and runs the control algorithm. Usually a microcontroller.

**PROCESS**

**Actuator**

A motor, heater, or valve that physically changes the system in response to the controller.

**OUTPUT**

**Feedback**

Closed-loop feeds the sensor reading back so the system self-corrects (thermostat). Open-loop has no feedback (timer fan).

**LOOP**

## FINAL PASS BEFORE THE EXAM

## Rapid exam tips

Eight things that lose marks in Paper 1 if you slip on them. Skim before you walk in.

**01**

The OS is more than a **UI**. It also manages processes, memory, files, devices, and security.

**02**

**FCFS** is simple but a long job blocks the queue. **Round robin** is fair, not fastest.

**03**

**Preemptive** can interrupt a process (round robin). **Non-preemptive** lets it finish (FCFS).

**04**

**Polling** loops to check; **interrupts** let a device signal and run an **ISR**.

**05**

Interrupts are not always better. **Polling** wins for frequent, predictable events.

**06**

A **sensor** measures input; an **actuator** changes output. Don't swap them.

**07**

**Open-loop** has no feedback; **closed-loop** self-corrects with a sensor.

**08**

Multitasking, virtual memory, paging, and **deadlock** (A1.3.5) are **HL only**.